B9145: Reliable Statistical Learning Hongseok Namkoong

# Causality

https://www.cambridge.org/core/books/causal-inference-for-statistics-social-and-biomedical-sciences/71126BE90C58F1A431FE9B2DD07938AB

https://scholar.harvard.edu/imbens/files/efficient\_estimation\_of\_average\_treatment\_effects\_using\_the\_estimated\_propensity\_score.pdf

https://onlinelibrary.wiley.com/doi/abs/10.1111/ectj.12097

https://www.pnas.org/content/116/10/4156

https://arxiv.org/pdf/1712.04912.pdf

#### Prediction and causality

- A central goal of ML is to predict an outcome given variables describing a situation
  - Given patient characteristics, will their outcome improve?
- Most decision-making problems revolve around a decision / intervention / treatment
  - What would happen if we changed the system?
  - Given patient characteristics, will their outcome improve if they follow a new diet?
- We want to develop a scientific understanding of a decision
  - If you predict housing demand based on price, then a prediction model will say high price means high demand

#### Prediction and causality

- Causal inference is a multi-disciplinary field built across economics, epidemiology, and statistics
- Focus is on questions about **counterfactuals** 
  - What structure of data do we need to answer this question?
  - How do we interpret the key estimands?
- ML models can predict outcomes; when can it predict counterfactuals?
  - How can we leverage flexible ML models to infer causality?

#### **Binary actions**

- Today we will focus on the setting with two actions
  - One action represents treatment (1), the other is control (0)
- This is still foundational
  - Key difficulties still persist here despite the simplicity
  - Core technical insights will translate to more general settings
- In complex problems, this is often the de facto standard
  - Control is status quo, treatment is a new elaborate program
  - Throughout economics, medicine, and tech, it requires a tremendous amount of domain knowledge and effort to come up with an alternative to the current system

#### Secret to life

The New York Times

#### Another Benefit to Going to Museums? You May Live Longer

Researchers in Britain found that people who go to museums, the theater and the opera were less likely to die in the study period than those who didn't.



B9145: Reliable Statistical Learning Hongseok Namkoong

### Causality

- You came up with a new diet regimen that you believe will alleviate symptoms of rheumatism (e.g. chronic joint pain)
- To test it, you recruit people to try the diet
- You find that
  - Small fraction on the diet experience chronic pain
  - Large fraction not on the diet (aka all rheumatism patients outside your volunteer pool) experience chronic pain
  - Awesome! Everyone should try this diet
- But after years of adoption, you realize the diet does not affect chronic pain

#### Causality

- What could have gone wrong?
  - Volunteers to the diet may have been people with healthy predispositions, and affluent socioeconomic backgrounds
- Fundamental problem: we don't observe counterfactuals
- How do we model this?

#### **Potential outcomes**

- Framework for explicitly modeling counterfactuals
- A: binary treatment assignment (1: treated, 0: control)
- Y(1) and Y(0) are potential outcomes
- X is observed covariates

First goal: Estimate average treatment effect  $\tau := \mathbb{E}[Y(1) - Y(0)]$ Point Asena Y((-A) Problem: We only observe Y := Y(A)

#### ATE

# First goal: Estimate average treatment effect $\tau := \mathbb{E}[Y(1) - Y(0)]$

- We only observe Y := Y(A)
- What could go wrong?
  - Volunteers to the diet (A = 1) may have been people with healthy predispositions, and affluent socioeconomic backgrounds

| Person | Α | Y(0) | Y(1) | Y(1) - Y(0) |
|--------|---|------|------|-------------|
| 1      | 1 | 0    | 0    | 0           |
| 2      | 1 | 0    | 0    | 0           |
| 3      | 1 | 0    | 0    | 0           |
| 4      | 1 | 0    | 0    | 0           |
| 5      | 0 | 1    | 1    | 0           |
| 6      | 0 | 1    | 1    | 0           |
| 7      | 0 | 1    | 1    | 0           |
| 8      | 0 | 1    | 1    | 0           |

#### Randomized control trials

also called A/B testing, (randomized) experiments

• First try: let's randomize treatment assignments

$$Y(1), Y(0) \perp A \neq Y = \Upsilon(A)$$

• By virtue of randomized assignments, we have

$$\tau = \mathbb{E}[Y(1) - Y(0)] = \mathbb{E}[Y(1) \mid A = 1] - \mathbb{E}[Y(0) \mid A = 0]$$

- $= \mathbb{E}[Y \mid A = 1] \mathbb{E}[Y \mid A = 0]$  observable
- We can estimate final line from i.i.d. data  $(Y_i, A_i)$

#### Randomized control trials

(Ti, Ai) üd



**Randomized control trials** CLT,  $Jn(\hat{z}-z) = ) N(0,6^2)$ by the where  $G^2 = V_{ar}(T|A=1) + V_{ar}(T|A=0) + 2Gr(...)$ = Var(Y(1)) + Var(Y(2)) +So for any estimator  $\hat{a}^2 + 6^2$ ,  $P\left(\frac{1}{2} - \frac{1}{3\pi} | \cdot 9b \leq z \leq \frac{1}{2} + \frac{1}{3\pi} | \cdot 9b \right) \rightarrow 0.95$ cf. Construct ôn2 by semple veriance of MA=a's.

#### **RCT** with covariates

- If by randomness more treatments get assigned to young patients with a better prognosis, then we will exaggerate the treatment effect
  - Problem goes away in large samples, but matters for small samples
- If you have access to covariates X, and can estimate  $\mathbb{E}[Y \mid X, A]$  accurately, then we can improve this
- Using any regression model, we can estimate  $\mathbb{E}[Y \mid X, A = 1], \mathbb{E}[Y \mid X, A = 0]$  observable
  - Random forests, boosted decision trees, kernels, NNs etc

#### Estimator

Vefine Ma(x) := ELY(a) |X], for a E E O, 13 tower law,  $Z = \mathbb{E}[Y(i) - Y(i)] = \mathbb{E}[H_i^*(x) - H_0^*(x)]$ By the Note that  $E[Y|X, A=\alpha] = E[Y(\alpha)|X, A=\alpha] = E[Y(\alpha)|X] = M_{\alpha}(x)$ Observable A 1 4(6),7(1),X is an estimater Ha Ma Y then  $\hat{z} = \frac{1}{n} \sum \hat{H}_i(X_i) - \hat{H}_i(X_i)$  is an estimator 77

#### Fitting outcome models

Has do we leave 
$$\mu_{n}^{*}$$
? Loss minimization  
min  
 $\Theta \in \Theta$   $\operatorname{He}\left((Y - \mu_{n}(X; \Theta))^{2} \mid A = a\right)$   
If  $\mu_{n}^{*}(\cdot) = \mu_{n}(\cdot; \Theta^{*})$   $\exists \Theta^{*} \in \Theta$ , then solving almost  
Via SGD finds a good estimation of  $\mu_{n}^{*}$ .

## **CLT for covariate adjustments** f Ma=Ma, than 2 is a good estimate For simplicity, if $\hat{\mathbf{n}} = \mathbf{M}^{\dagger}$ , $\mathbb{E}_{2}^{2} = \mathbb{E}\left[\frac{1}{2}\sum_{i=1}^{n} M_{i}^{*}(x_{i}) - M_{i}^{*}(x_{i})\right] = 7$ By the CLT, $\frac{Jn}{4}(\hat{z}-z) \Rightarrow \mathcal{N}(o,1)$ where $A_n^2$ is the sample science of $(\mu_i^+ \mu_i^-)(\chi)$ .

### **Beyond RCTs**

- What if clean randomization is not possible?
- Randomization sometimes affected by the site
  - Oxford / AstraZeneca trial made a dosage mistake at a location
  - Turned out to be more effective
- Ignoring variables that affect treatment assignment leads to biases

### **Beyond RCTs**

• Run large-scale experiment, randomized for each sex

|                       | Men        |         | Women      |         |
|-----------------------|------------|---------|------------|---------|
|                       | No disease | Disease | No disease | Disease |
|                       | (Y = 1)    | (Y=0)   | (Y=1)      | (Y=0)   |
| Treatment ( $A = 1$ ) | 0.1500     | 0.2250  | 0.1000     | 0.0250  |
| Control ( $A = 0$ )   | 0.0375     | 0.0875  | 0.2625     | 0.1125  |

(Here the numbers are the fractions of individuals in each category.)

- $\mathbb{P}(Y=1 \mid A=1) = 0.5$  vs  $\mathbb{P}(Y=1 \mid A=0) = 0.6$ 
  - So maybe treatment is not effective?

#### Simpson's paradox

• But if you compute treatment effect for each sexes,

 $\mathbb{E}[Y(1) - Y(0) \mid X = m] = \mathbb{E}[Y(1) - Y(0) \mid X = w] = 0.1$ 

- So ATE = 0.1. What happened?
- Women are more likely to be in control than treatment; men are more likely to be in treatment than control. And women have higher potential outcomes on average than men.

#### Simpson's paradox

• Issue here is that

 $\mathbb{E}[Y(1) - Y(0)] \neq \mathbb{E}[Y \mid A = 1] - \mathbb{E}[Y \mid A = 0]$ 

If you ignore sex as a confounding variable, you create a omitted variable bias in estimating the ATE

#### **Berkeley admissions**

- Berkeley was sued for gender bias in admissions based on 1973 numbers: 44% of men were admitted but only 35% of women
- But individual department's admissions record showed no evidence of such gender-based discrimination
- Turns out women systematically applied to more competitive majors

#### **Observational studies**

- Randomization is sometimes infeasible or prohibitively expensive
  - e.g. post-market drug surveillance, effect of air pollution on longterm health outcomes
- Experimentation can be risky in high-stakes scenarios
  - operational scenarios: new inventory policy for Amazon, new pricing algorithm for Uber
- May want to use existing large-scale data collected under some data-generating policy (e.g. legacy system)

### No unobserved confounding

• Previous regression-based direct method still works if there are no unobserved confounders (also called ignorability)

#### **Assumption.** $Y(1), Y(0) \perp A \mid X$

- Observed treatment assignments are based on covariate information alone (+ random noise)
  - Treatment assignment does not use information about counterfactuals
- Strong assumption. Often violated in practice.
  - e.g. doctors often use unrecorded info to prescribe treatments

#### No unobserved confounding Z(X):= 町(1)-T(-) |X] = $\mathbb{E}[\Upsilon(I)[X, A=I] - \mathbb{E}[\Upsilon(I)][X, A=I]$ we undescoved out. = E[Y|X,A=1] - E[Y|X,A=0] since (= ((A) obsemable

### Overlap

- We need enough samples for both control and treatment throughout the covariate space
  - This governs the effective sample size
- Propensity score  $e^{\star}(X) := \mathbb{P}(A = 1 \mid X)$
- Assume that there exists  $\epsilon > 0$  such that  $\epsilon \le e^{\star}(X) \le 1 \epsilon$  almost surely
- This means I have at least  $\epsilon n$  number of samples for fitting the two outcome models

### Overlap

- This breaks if data is generated by a deterministic policy
  - e.g. always assign the drug (treatment) when age > 50
- We need sufficient amount of randomness in treatment assignment in all covariate regions
- Governs difficulty of estimation. Often violated in practice.

Direct method  
As byre estimate 
$$\mu_{\alpha}^{*}(x) := E[T(c) |x]$$
  
By no modes. confirmeding,  
 $E[T(a)|x] = E[T|X, A=a]$   
so we can use any black-lass only model to get  
so ght data:  
On first churk, fit  $\hat{M}_{\alpha}(x) = a=0,1$   
on second churk, use  $\hat{\mu}_{\alpha}$  to estimate z

#### **Direct method**



works well if phi is easy to estimate

#### Inverse propensity weighting

- What if the outcome models are very complex and difficult to estimate?
- A natural approach is to reweight samples, to change the distribution  $\mathbb{E}[\cdot | A = 1, X]$  to  $\mathbb{E}[\cdot | X]$

- Essentially importance sampling

 $e^{+}(x) := P(A=1|x) : prop sure$   $\hat{z}_{1PL} = \frac{1}{n} \sum_{i}^{n} \frac{A_{i}T_{i}}{e^{+}(x_{i})} - \frac{(1-A_{i})T_{i}}{1-e^{+}(x_{i})} \quad \text{if } e^{+} \text{ known.}$ If  $e^{+}$  unknown, replace  $e^{+}$  with an estimate  $\hat{e}^{+}$ .

#### Unbiasedness $e^{(x)} := P(A=1|x)$ Ŀ prop sure $\frac{1}{n}\sum_{i=1}^{n}\frac{A_{i}T_{i}}{e^{r}(K_{i})} = \frac{(1-A_{i})T_{i}}{(1-A_{i})T_{i}}$ ZIPL = f(x) = f(x) = f(x) [x] = f(x) [x] = f(x) [x, A=1] $= \overrightarrow{\mathrm{H}} \overrightarrow{\mathrm{H}} \times, A=i ] = \overrightarrow{\mathrm{H}} \overrightarrow{\mathrm{H}} \overrightarrow{\mathrm{H}} \times, A=i ] / (i=T(A))$ = EFEF(() [x]] by no wrobs. cont. MO.H-) #A X FITON

#### **CLT for IPW**

By at 
$$Jr(Z_{PD}-Z) = N(0, G_{PD})$$
  
 $G_{PD}^{2} = Vcs\left(\frac{AT}{C(\kappa)} + \frac{FA}{1-et(\kappa)}\right)$   
 $= Vcs\left(\frac{AT}{C(\kappa)} + Vcr\left(\frac{(J-A)T}{(-eT\kappa)}\right) - z E[fr(i)]E[fr(i)]$   
Take  $L_{i}^{2}$  as cample scance of  $\frac{AT}{e'(\kappa)} - \frac{(J-A)T}{1-et(\kappa)}$   
then  $P(Z \in [Z_{PD} \pm \frac{An}{JA}] - b] \rightarrow q5^{-1}$ .



#### Inverse propensity weighting

- Can work well if propensity score is simple to estimate
- But estimating this well over the entire covariate space can be difficult
  - Calibration is hard, especially in high-dimensions
- When overlap doesn't hold, importance weights blow up

### Augmented IPW

- Can we combine the best of both worlds?
  - Direct method + IPW
- Propensity weight residuals to debias the direct method

$$\frac{A}{2HPW} := \frac{1}{n} \sum_{i}^{n} \left\{ \frac{W_{i}^{*}(K_{i}) - M_{i}^{*}(K_{i})}{(-e^{*}(K_{i}))} + \frac{A_{i}}{e^{*}(K_{i})} \left(\frac{\pi}{1 - e^{*}(K_{i})} - \frac{(-A_{i})}{1 - e^{*}(K_{i})}\right) \right\}$$

$$= \frac{1}{n} \sum_{i}^{n} \left\{ \frac{A_{i}T_{i}}{e^{*}(K_{i})} - \frac{(1 - A_{i})T_{i}}{(-e^{*}(K_{i}))} + \left(1 - \frac{A}{e^{*}(K_{i})}\right) H_{i}^{*}(K_{i}) - \left(1 - \frac{\pi}{1 - e^{*}(K_{i})}\right) H_{i}^{*}(K_{i}) \right\}$$

$$\frac{W}{W}$$

$$\frac{W}{W}$$

(X,A,Y)

#### Unbiasedness



$$\begin{split} \mathbb{E}[\mathsf{M}^{i}(\mathsf{x})-\mathsf{M}^{s}(\mathsf{x})] &= \mathbb{P}(\mathsf{A}=\mathsf{I}(\mathsf{x}))\mathbb{E}[\stackrel{\mathsf{A}}{=\mathsf{f}(\mathsf{x})}(\mathsf{T}-\mathsf{M}^{i}(\mathsf{x}))|\mathsf{X},\mathsf{A}=\mathsf{I}] \\ &= \mathbb{E}[\mathsf{T}(\mathsf{T}-\mathsf{M}^{i}(\mathsf{x})|\mathsf{X},\mathsf{A}=\mathsf{I}] = \mathbb{E}[\mathsf{T}(\mathsf{I})-\mathsf{M}^{s}(\mathsf{x})|\mathsf{X},\mathsf{A}=\mathsf{I}] \\ &= \mathbb{E}[\mathsf{T}(\mathsf{I})-\mathsf{M}^{s}(\mathsf{x})|\mathsf{X},\mathsf{A}=\mathsf{I}] = \mathbb{E}[\mathsf{T}(\mathsf{I})-\mathsf{M}^{s}(\mathsf{x})|\mathsf{X},\mathsf{A}=\mathsf{I}] \\ &= \mathbb{E}[\mathsf{T}(\mathsf{I})-\mathsf{M}^{s}(\mathsf{x})|\mathsf{X}] \quad \text{by no undes. conf.} = \mathbb{C}[\mathsf{T}(\mathsf{I})-\mathsf{M}^{s}(\mathsf{x})|\mathsf{X}] \end{split}$$

#### **CLT for AIPW**

$$\frac{\sqrt{2}}{\sqrt{2}}\left(\frac{2}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)-\frac{1}{\sqrt{2}}\right)=\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}\right)-\frac{1}{\sqrt{2}}\right)$$

is the sample variable of where  $S_n^2$ 

$$\frac{A_{i}T_{i}}{e^{r}(K_{i})} \frac{(1-A_{i})T_{i}}{(-e^{r}(K_{i}))} + \left(1-\frac{A}{e^{r}(K_{i})}\right)\mu_{i}^{*}(K_{i}) - \left(1-\frac{1-A_{i}}{1-e^{r}(K_{i})}\right)\mu_{i}^{*}(K_{i})$$

#### **Control variate**

Another interpretation of APW is that the aug. term is a control variate.

$$V_{\alpha \sigma}\left(\frac{A\gamma}{e^{t}(x)}+\left(1-\frac{A}{e^{t}(x)}\right)\mu^{t}(x)\right)$$

$$= V_{cr} \left( \frac{A^{r}}{e^{t}(x)} \right) + V_{cr} \left( \left( I - \frac{A}{e^{t}(x)} \right) H_{i}^{*}(x) \right) + 2 c_{ov} \left( \frac{A^{r}}{e^{t}(x)} , \left( I - \frac{A}{e^{t}(r)} \right) H_{i}^{*}(k) \right)$$
$$= V_{cr} \left( \frac{A^{r}}{e^{t}(x)} \right) - V_{cr} \left( \left( I - \frac{A}{e^{t}(x)} \right) H_{i}^{*}(x) \right)$$

#### **Control variate**

#### Efficiency

- In fact, this is the best asymptotic variance we can get
- AIPW has optimal asymptotic variance, regardless of whether the propensity score is known or not
- Formalizing this requires a lot of work

Nuisance parameters  

$$\mu_{a}^{*}(x) \coloneqq \mathbb{E}[T^{(a)}|x] = \mathbb{E}[T^{(x)}, A=a]$$
  
 $\mathbb{E}[Y|X, A=a]$   
No undos. anf.  
 $e^{*}(x) \coloneqq \mathbb{P}(A=||x|)$ 

- If a good parametric model exists, then can estimate at the usual  $1/\sqrt{n}$  rates
- In general, these are infinite dimensional objects. Can be difficult to estimate.

#### Semiparametrics

- We only care about estimating the ATE
  - One-dimensional estimand, infinite dimensional nuisance parameters
- Estimation accuracy of nuisance parameters is good only insofar as it helps with estimating the ATE
- Due to its high-dimensional nature, often difficult to estimate nuisances at parametric rates
- Goal: semiparametric estimators that are insensitive to errors in nuisance estimates

#### **Doubly robust**

 One main advantage of AIPW is that even if one of the nuisance parameter models are misspecified, you can still get correct asymptotic behavior

Empu := 
$$\int_{n} \sum_{i} \left\{ \mu_{i}(K_{i}) + \mu_{i}(K_{i}) + \frac{\Lambda_{i}}{e^{T}(K_{i})} (T_{i} - M_{i}(K_{i})) - \frac{(-\Lambda_{i}}{1 - e^{T}(K_{i})} (T_{i} - H_{i}(K_{i})) \right\} \right\}$$
Assure  $\hat{c} \in [E_{i}, E_{i}]$  a.s.
Dif  $\hat{e}$  is learned from a well-specified model class, then  $\|\hat{e} - e^{T}\|_{P_{i}}^{P_{i}}$ 
Let's any antime models are mis-specified so  $(\hat{H}_{a} - \mu_{a}\|_{P_{i}}^{2} + 0, \mu_{a} + M_{a}^{*})$ 
End  $\hat{F}$  Z
Dif  $\hat{H}$   $\hat{M}_{a}$  is well-specified, then  $\|\hat{M}_{a} - \mu_{a}\|_{P_{i}}^{2} + 0$ 
Let's any antime models are mis-specified so  $(\hat{H}_{a} - \mu_{a}\|_{P_{i}}^{2} + 0, \mu_{a} + M_{a}^{*})$ 
End  $\hat{F}$  Z
Difficult equations is misspecified so  $V\hat{e} - e^{T}\|_{P_{i}}^{2} + 0$ 
Let's any and specified is misspecified so  $V\hat{e} - e^{T}\|_{P_{i}}^{2} + 0$ 
Let's any and specified is misspecified so  $V\hat{e} - e^{T}\|_{P_{i}}^{2} + 0$ 
Let's any and specified is misspecified so  $V\hat{e} - e^{T}\|_{P_{i}}^{2} + 0$ 
Let's and  $\hat{F}$  Z
End (K\_{i}) = \frac{1}{2} + \frac{1}

B9145: Reliable Statistical Learning Hongseok Namkoong

#### **Doubly robust**

B9145: Reliable Statistical Learning Hongseok Namkoong

### Orthogonality

- When is a semiparametric estimator insensitive to errors in nuisance estimates?
- Directional derivative of functional wrt nuisance parameters at true value is near-zero
- Ensures that a little perturbation in nuisance parameters near the truth values does not affect functional

B9145: Reliable Statistical Learning Hongseok Namkoong

٦

$$\begin{array}{l} & \text{Orthogonality of AIPW} \\ & \text{Assure } \oint_{dr} \& E_{p} & \text{are interchangeable Humanhant} \\ & \oint_{dr} E_{p} \left( \text{Nitr}(n_{1}-n_{1}^{*}))(x_{1}\right) \Big|_{r=0} & = E\left[ \left( \mu_{1} - \mu_{1}^{*} \right)(x_{1} \right] & \text{First} \\ & \oint_{dr} E_{p} \left[ \frac{A}{(e^{-e^{-}})} \left( Y - (n^{*}+r^{*}n_{1}-n^{*}))(x_{1} \right) \right] \Big|_{r=0} & \text{Second} \\ & = -E\left[ \frac{A(e-e^{-})}{(e^{+}r^{*}(e-e^{-}))^{2}} \left( Y - \mu_{1}^{*}(x_{1}) \right] \Big|_{r=0} - E\left[ \frac{A}{e^{-}(x_{1})} \left( n_{1}-n_{1}^{*}\right)(x_{1} \right] \right] \\ & = -E\left[ \frac{A(e-e^{-})}{(e^{+}x^{*}(x_{1})^{2}} \left( Y - \mu_{1}^{*}(x_{1}) \right) \right] - E\left[ \frac{A}{e^{-}(x_{1})} \left( n_{1}-n_{1}^{*}\right)(x_{1} \right] \right] \\ & = -E\left[ \frac{A(e-e^{-})(x_{1})}{(e^{+}x^{*}(x_{1})^{2}} \left( (Y - \mu_{1}^{*}(x_{1})) \right] - E\left[ \frac{A}{e^{-}(x_{1})} \left( n_{1}-n_{1}^{*}\right)(x_{1} \right] \right] \\ & = -E\left[ \frac{A(e-e^{-})(x_{1})}{(e^{+}x^{*})} \left( (Y - \mu_{1}^{*}(x_{1})) \right] X \right] - E\left[ (\mu_{1}-n_{1}^{*}(x_{1})) \right] \\ & = -E\left[ \frac{(e-e^{-})(x_{1})}{(e^{+}x^{*})} \right] \\ & = -E\left[ \frac{(e-e^{-})(x_{1})}{(e^{+}x^{*})} \right] \\ & = -E\left[ (\mu_{1}-n_{1}^{*})(x_{1}) \right] \end{aligned}$$

B9145: Reliable Statistical Learning Hongseok Namkoong

#### Orthogonality of AIPW

#### Why orthogonality? $(n^{-\frac{1}{2r+d}})$ $\frac{1}{2r+d}$ $\frac{1}{2r+d}$ $\frac{1}{2r+d}$

- Allows getting central limit rates on ATE estimation even when we can only estimate nuisance parameters at slower rates
- In addition to no unobserved confounding,  $e^{\star}(X), \hat{e}(X) \in [\epsilon, 1 - \epsilon]$ , we assume the following rate condition

$$\left\{ \|\hat{e} - e^{\star}\|_{P,2} (\|\hat{\mu}_1 - \mu_1^{\star}\|_{P,2} + \|\hat{\mu}_0 - \mu_0^{\star}\|_{P,2}) = o_p(n^{-1/2}) \right\}$$

• This allows us to trade-off errors between nuisance parameters. Only their product needs to go down at this rate!

#### Central limit result

 CLT for the semiparametric AIPW, even when nuisance estimates converge at slower-than-parametric rates

$$\sqrt{n} \left( \frac{1}{n} \sum_{i=1}^{n} \psi_{\text{AIPW}}(X_i, Y_i, A_i; \hat{\mu}_0, \hat{\mu}_1, \hat{e}) - \tau \right) \Rightarrow N(0, \sigma_{\text{AIPW}}^2)$$

where 
$$\sigma_{\text{AIPW}}^2 := \text{Var}\left(\psi_{\text{AIPW}}\left(X, Y, A; \mu_0^{\star}, \mu_1^{\star}, e^{\star}\right)\right)$$

- This is the oracle asymptotic variance; when the true nuisance parameters are known
- AIPW achieves optimal asymptotic efficiency

Sketch of asymptotics  

$$D = (K,T, A)$$
  $\eta = (M,M,e)$   
 $Jn(A \equiv \Psi(0; in) - EY(Din^{*})) =) N(A \delta_{AIPL}^{2})$   
 $\frac{1}{R} \equiv \Psi(0; in) - E_{PAP} \Psi(Din) + E_{Dip} \Psi(Din) - EY(Din^{*})$   
 $Jn = 0$   $D$   $N(D, \delta_{AIPL}^{2})$   $Jn = EY(Din^{*})$   
 $Un = 0$   $N(D, \delta_{AIPL}^{2})$   $Jn = 0$ .  
 $Eofine R(r) := E_{Dip} \Psi(Din + r(n - n^{*}))$   
 $(B) = B(i) - E(0)$  If  $r \mapsto R(r)$  is conta diff,  
 $= R'(r) \cdot (i - \delta)$  for some  $r \in Gai$   
So move we want to argue that  $Jn = P'(r) \stackrel{r}{\to} D$ 

# Sketch of asymptotics By orthogonality, $\mathcal{R}'(o) = D$ . If $\mathcal{R}'$ is smooth enough, then $Jn \sup_{r \in [n]} \mathcal{R}'(r) \stackrel{r}{\rightarrow} o$ as long as rate endution.

# **Cross-fitting**

 Instead of sample-splitting, we can alternate the role of main and auxiliary samples over multiple splits



Estimate nuisance parameters on the auxiliary sample

# **Cross-fitting**



$$\hat{\tau}_1 := \frac{1}{n} \sum_{i=1}^n \hat{\mu}_1(X_i) - \hat{\mu}_0(X_i) + \frac{A_i}{\hat{e}(X_i)} (Y - \mu_1(X_i)) - \frac{1 - A_i}{1 - \hat{e}(X_i)} (Y - \mu_0(X_i))$$

Estimate ATE by plugging in nuisance estimates

# **Cross-fitting**



- Same procedure for direct method, IPW
- Similar central limit result follows as before