#### **B9145:** Reliable Statistical Learning

Spring 2023

### Lecture 5: Distributionally Robust Optimization

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## 5.1 Distributionally Robust Optimization (DRO) Setup

As in previous lectures, let  $\Theta \subseteq \mathbb{R}^d$  be the model class or decision space,  $\mathcal{Z}$  be the data domain, and  $\ell: \Theta \times \mathcal{Z} \to \mathbb{R}$  be a loss function representing statistical prediction error. Let P be the data generating distribution over  $\mathcal{Z}$ , so  $Z \sim P$  is a draw of random data. Our typical learning problem minimizes average risk (or, henceforth, just risk):

$$\min_{\theta \in \Theta} R(\theta) := \min_{\theta \in \Theta} \mathbb{E}_P[\ell(\theta; Z)]. \tag{5.1}$$

If the data-generating distribution P is sufficiently representative of the population of interest, (5.1) is effective. However, this requirement is frequently violated, as in the following real-world examples:

- Data is often collected from a particular set of geospatial locations, and may not be representative of the entire population of interest. For instance, Figure 5.1 plots the demographic compositions of low-income adults in Oregon and Texas.
- Even small shifts in the environment (as in image classification in ImageNet) degrade the performance of state-of-the-art models, up to 11-14% for average-case risk.
- Machine learning systems deterioriate on subpopulations and underrepresented user groups in datasets (possibly reflecting societal biases) in applications as varied as: speech reconigtion, facial reconition, video captioning, language identification, and recommender systems.

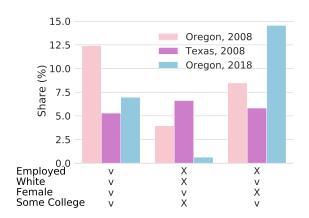


Figure 5.1: Demographics of low-income adults.

Instead of taking the average-case approach of (5.1), we consider a worst-case approach. Given a set Q of probability distributions, we minimize the worst-case expected loss over distributions  $Q \in Q$ :

$$\min_{\theta \in \Theta} \sup_{Q \in \mathcal{Q}} \mathbb{E}_{Q}[\ell(\theta; Z)]. \tag{5.2}$$

This is distributionally robust optimization (DRO). For a fixed model  $\theta \in \Theta$ , we interpret this as an adversary playing the worst distribution Q for that model. Of course, we should ask the question: what does the set Q of distributions include?

In this lecture, we will explore distributional robustness in a neighborhood around the data-generating distribution P. This is a natural goal for prediction problems where we are interested in learning models  $\theta$  that perform uniformly well across small perturbations to the data-generating distribution. We define what we mean by a "neighborhood" in the sequel.

Before we move on, we also consider briefly what it means to optimize the *sample risk*, the empirical estimate of (5.1):

$$\min_{\theta \in \Theta} \widehat{R}(\theta) := \sum_{i=1}^{n} \frac{1}{n} \ell(\theta; Z_i), \tag{5.3}$$

where  $Z_1, \ldots, Z_n$  are i.i.d. data drawn from P. We may view the  $\frac{1}{n}$  as a uniform weighting over the losses of each example,  $\ell(\theta; Z_i)$ . Instead, in the DRO framework, we might generalize this to assign different weights to each  $\ell(\theta; Z_i)$ , as follows:

$$\min_{\theta \in \Theta} \sup_{p \in \mathcal{P}_n} \sum_{i=1}^n p_i \ell(\theta; Z_i), \tag{5.4}$$

where  $\mathcal{P}_n$  is an appropriately chosen set of n-vectors. We will explore (5.4) in the sequel.

### 5.2 f-Divergences

We begin by defining the notion of an f-divergence, a notion of closeness between two distributions using a convex function f.

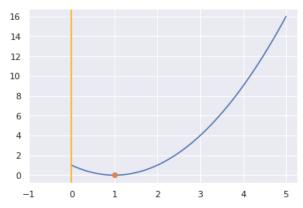
**Definition 1** (f-divergence). Let  $f: \mathbb{R} \to \overline{\mathbb{R}}_+ = \mathbb{R}_+ \cup \{\infty\}$  be a convex function satisfying f(1) = 0 and  $f(t) = +\infty$  for any t < 0. Then, the f-divergence between distributions Q and P is:

$$D_f(Q||P) := \int f\left(\frac{dQ}{dP}\right) dP.$$

This is a general notion that, for different choices of f, give us familiar notions of distance between distributions. For example:

- $f(t) = t \log t$  gives KL-divergence.
- f(t) = |t 1| gives total variation distance.
- $f(t) = (t-1)^2$  gives  $\chi^2$  divergence.

One should think of f-divergences in terms of the simple picture in Figure 5.2. When distributions are equal, the f divergence always evaluates to 0. When the ratio between dQ and dP increases, i.e. when Q is sufficiently different from P, the f-divergence blows up.



**Figure 5.2.**  $f(t) = (t-1)^2$ , the convex function that  $\chi^2$  divergence is based on. To the left of t = 0 (indicated by the yellow line), the function takes value  $f(t) = \infty$ .

Using the tool of f-divergence, we may now properly define the set Q of "close" distributions and the "neighborhood" discussed in Section 5.1. The distributionally robust optimization problem minimizes, for some fixed distribution P, f-divergence, and radius  $\rho$ :

$$\min_{\theta \in \Theta} \left\{ R_f(\theta; P) := \sup_{Q \ll P} \left\{ \mathbb{E}_Q[\ell(\theta; Z)] : D_f(Q \| P) \le \rho \right\} \right\}. \tag{5.5}$$

Note that, here, there are two main parameters defining the collection of distributions of interest, Q: (1)  $\rho$ , the radius/magnitude for the unknown distribution shift and (2) f, the choice of distance between distributions. In practice, these are nontrivial to choose, for nailing down *all* distributions of interest in real-world problems is difficult (and not even clearly captured by f and  $\rho$ ). A couple other remarks:

- f-divergence limits us to using distributions Q that have the same support as P. In future lecture, we will relax this with a different family of distances (Wasserstein).
- (5.5) has the effect of upweighting regions of  $\mathcal{Z}$  with high losses  $\ell(\theta; Z)$ . That is, it optimizes the performance of  $\theta$  on the tails or the "hard" examples. (5.4) above suggests this, and the duality derivation in Section 5.2.1 makes this clear as well.

#### 5.2.1 Duality Formulation of DRO

By itself, the inner optimization in (5.5) seems intractable, so we will reformulate the problem through duality. This gives us the following important proposition.

**Proposition 1** (Duality of DRO). Let P be a probability measure on  $\mathcal{Z}$  and  $\rho > 0$ . Let  $f^*$  be the Fenchel conjugate of f,

$$f^*(s) := \sup_{t} \{st - f(t)\}.$$

Then,

$$R_f(\theta; P) = \inf_{\lambda \ge 0, \eta \in \mathbb{R}} \left\{ \lambda \mathbb{E}_P \left[ f^* \left( \frac{\ell(\theta; Z) - \eta}{\lambda} \right) \right] + \lambda \rho + \eta \right\}$$
 (5.6)

for all  $\theta$ . Moreover, if the supremum on the left hand side is finite, there are finite  $\lambda(\theta) \geq 0$  and  $\eta(\theta) \in \mathbb{R}$  attaining the infimum on the right hand side.

*Proof.* Fix some  $\theta \in \Theta$  and distribution P. We redefine (5.5) in terms of the likelihood ratio,  $L(Z) := \frac{dQ(Z)}{dP(Z)}$ . This gives us:

$$R_f(\theta; P) = \sup_{L>0} \{ \mathbb{E}_P[L(Z)\ell(\theta; Z)] : \mathbb{E}_P[f(L(Z))] \le \rho, \mathbb{E}_P[L(Z)] = 1 \}.$$
 (5.7)

From Lagrangian duality, we will assign  $\lambda \geq 0$  to the constraint  $\mathbb{E}_P[f(L(Z))] \leq \rho$  and  $\eta \in \mathbb{R}$  to  $\mathbb{E}_P[L(Z)] = 1$ , so:

$$= \sup_{L>0} \inf_{\lambda \geq 0, \eta \in \mathbb{R}} \left\{ \mathbb{E}_P[L(Z)\ell(\theta; Z)] + \lambda(\rho - \mathbb{E}_P[f(L(Z))] - \eta(\mathbb{E}_P[L(Z)] - 1) \right\}$$

Taking  $L \equiv 1$  gives us  $\mathbb{E}_P[f(L)] = 0$  and  $\mathbb{E}_P[L] = 1$  so the extended Slater condition holds and we can switch the order of the inf and sup. After doing this and rearranging, we obtain:

$$= \inf_{\lambda \ge 0, \eta \in \mathbb{R}} \sup_{L \ge 0} \left\{ \mathbb{E}_{P}[L(Z)\ell(\theta; Z) - \lambda f(L(Z)) - \eta L(Z)] \right\} + \lambda \rho + \eta$$

$$= \inf_{\lambda \ge 0, \eta \in \mathbb{R}} \sup_{L \ge 0} \left\{ \lambda \mathbb{E}_{P} \left[ \frac{L(Z)(\ell(\theta; Z) - \eta)}{\lambda} - f(L(Z)) \right] \right\} + \lambda \rho + \eta.$$
(5.8)

Notice that  $L: \mathcal{Z} \to \mathbb{R}_+$  is an arbitrary nonnegative measurable function that we are taking a supremum over. This allows us to interchange the inner supremum and the integral, giving us the Fenchel conjugate:

$$\begin{split} \sup_{L \geq 0} \mathbb{E}_P \left[ \frac{L(Z)(\ell(\theta; Z) - \eta)}{\lambda} - f(L(Z)) \right] &= \sup_{L \geq 0} \int_{\mathcal{Z}} \frac{L(Z)(\ell(\theta; Z) - \eta)}{\lambda} - f(L(Z)) dP \\ &= \int_{\mathcal{Z}} \sup_{L \geq 0} \left\{ L\left(\frac{\ell(\theta; Z) - \eta}{\lambda}\right) - f(L) \right\} dP \\ &= \int_{\mathcal{Z}} f^* \left(\frac{\ell(\theta; Z) - \eta}{\lambda}\right) dP \\ &= \mathbb{E}_P \left[ f^* \left(\frac{\ell(\theta; Z) - \eta}{\lambda}\right) \right]. \end{split}$$

Plugging this back into (5.8) gives us our desired result.

As a concrete example of Proposition 1, consider divergences that look like  $t^k$ . Specifically, for  $k \in (1, \infty)$ , we consider the Cressie-Read family of divergences, defined as:

$$f_k(t) := \begin{cases} t^k - 1 & \text{if } t \ge 0\\ \infty & \text{otherwise} \end{cases}$$
 (5.9)

Denoting  $k_* = \frac{k}{k+1}$  and  $(s)_+ = \max(s,0)$ , we obtain the following Fenchel conjugate,

$$f_k^*(s) = k^{-k_*}(k-1)(s)_+^{k_*} + 1. (5.10)$$

Applying Proposition 1, we obtain:

$$R_f(\theta; P) = \inf_{\lambda > 0, \eta \in \mathbb{R}} \left\{ \lambda^{1 - k_*} k^{-k_*} (k - 1) \mathbb{E}_P \left[ (\ell(\theta; Z) - \eta)_+^{k_*} \right] + \lambda(\rho + 1) + \eta \right\}$$

Now, optimizing over  $\lambda \geq 0$  and denoting  $c_k(\rho) := (1+\rho)^{\frac{1}{k}}$ , we obtain the final dual form:

$$R_k(\theta; P) = \inf_{\eta \in \mathbb{R}} \left\{ c_k(\rho) \mathbb{E}_P \left[ (\ell(\theta; Z) - \eta)_+^{k_*} \right]^{\frac{1}{k^*}} + \eta \right\}$$
 (5.11)

Thus, in this particular case of Cressie-Read f-divergences, the simplified form above shows that distributional robustness is equivalent to optimizing the tail performance of the model.  $\eta$  is the threshold at which we care about the loss of an example; for examples with loss less than  $\eta$ , the expectation in (5.11) vanishes. Thus, the harder examples (with loss greater than  $\eta$ ) are emphasized by a power of  $k_*$ .

# Variation in error over 120 class

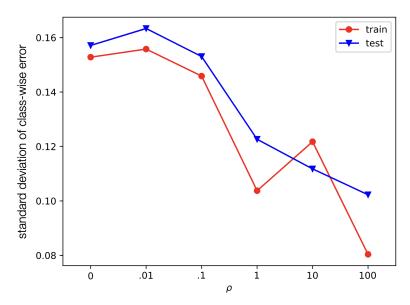


Figure 5.3. Variation in error over all the classes. As  $\rho$  increases (DRO hedges against further distributions), we see that the variation in class-wise error becomes smaller; the error rates become more uniform through the classes.

# 5.3 Optimizing DRO in Practice

The following section of notes are at a higher level – in this portion of the lecture, we discussed how DRO works in practice and its pros and cons. First, to actually operationalize (5.5) in practice, we of course do not have access to population distributions, so we must use an empirical plug-in. Suppose we have a finite sample of data  $\{Z_i\}_{i=1}^n$ . The empirical plug-in formulation of the primal is:

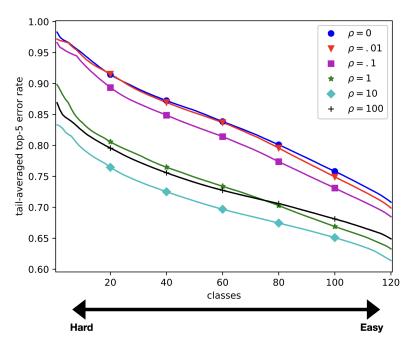
$$\sup_{q} \left\{ \sum_{i=1}^{n} q_{i} \ell(\theta; Z_{i}) : D_{f}(q \| \mathbf{1}/n) \leq \rho, q^{\top} \mathbf{1} = 1, q_{i} \geq 0 \right\}.$$
 (5.12)

To optimize this, we can play a 2-player stochastic game (adversary plays q and the player plays  $\theta \in \Theta$ ), or just do batch gradient descent on the whole thing. Alternatively, we can optimize the empirical formulation of the dual in (5.6) using a standard solver.

However, how does DRO perform in practice? In lecture, we looked at an experiment for fine-grained recognition. The taks was to classify images of dogs to dog breeds (with 120 breeds/classes total). In the dataset, there was no underrepresentation: each breed/class had the same number of images. The experiment used DRO with  $\chi^2$  divergence, parametrized with  $\rho > 0$  as the magnitude of distance between distributions.

In Figure 5.3, we see that performing DRO with a significant  $\rho$  parameter decreases the variation in error across the classes. In Figure 5.4, we actually see that DRO in this specific experiment actually consistently does better than the standard average-case risk minimization, *even* when we are accounting for every single class. This suggests that, at least in some cases, DRO is useful even for the original goal of average-case risk minimization (5.1). This motivates Section 5.4

# Worst x-classes



**Figure 5.4.** Top-5 error rate across x classes. On the far left is top-5 error rate on the hardest 20 classes; on the far right is the top-5 error rate over all classes. Each curve represents DRO at level  $\rho \geq 0$ ;  $\rho = 0$  is standard average-case risk minimization.

### 5.4 Equivalence of DRO and Variance Regularization

In Section 5.3, we observed that, at least in this specific experiment, applying DRO actually helped with the original goal of standard average-case risk minimization. Recall the classical notion of (average-case) risk for a data-generating distribution P, which we rewrite here for convenience:

$$R(\theta) = \mathbb{E}_P[\ell(\theta; Z)] \tag{5.13}$$

for  $Z \sim P$ .

This raises the question: does DRO provide any guarantees for our *original* (classical) goal of minimizing average-case risk (5.13)? In this section, forget all about the goal of robust optimization to distribution shifts; we return to our classical goal of minimizing standard average-risk. We will show a theoretical result that DRO helps in this classical goal.

Fix some data-generating distribution P. The standard approach for minimizing risk in statistical learning is ERM. That is, we find the model  $\hat{\theta}^{\text{erm}} \in \Theta$  that minimizes the average-case sample risk:

$$\hat{\theta}^{\text{erm}} \in \operatorname*{argmin}_{\theta \in \Theta} \widehat{R}_n(\theta) := \frac{1}{n} \sum_{i=1}^n \ell(\theta; Z_i),$$

for a dataset  $\{Z_i\}_{i=1}^n$  all drawn i.i.d. from P. The hope is that  $\widehat{R}_n(\theta)$  is a good approximation of  $R(\theta)$ .

From the empirical Bernstein's inequality, with probability  $1 - \delta$ ,

$$R(\theta) = \mathbb{E}_{P}[\ell(\theta; Z)] \leq \underbrace{\widehat{R}_{n}(\theta)}_{\text{bias}} + \underbrace{\sqrt{\frac{2\text{Var}_{\widehat{P}_{n}}(\ell(\theta; Z))}{n}}}_{\text{variance}} + \frac{C\log\frac{1}{\delta}}{n}.$$
 (5.14)

Above,  $\operatorname{Var}_{\widehat{P}_n}$  is empirical variance. Any estimator has a bias and variance, and (5.14) makes this explicit. We might hope to use this upper bound directly (optimally trading off between bias and variance) by solving this variance-regularized sample risk.

$$\hat{\theta}^{\text{var}} \in \underset{\theta \in \Theta}{\operatorname{argmin}} \left\{ \widehat{R}_n(\theta) + \sqrt{\frac{2\operatorname{Var}_{\widehat{P}_n}(\ell(\theta; Z))}{n}} \right\}. \tag{5.15}$$

The problem is that we cannot solve 5.15 through standard optimization methods because it is non-convex. However, skipping to the punchline, it will happen that using DRO with a specific setup will allow us to minimize 5.15.

We will setup the DRO problem now. Fix some P, and draw a dataset of n examples  $\{Z_i\}_{i=1}^n$  i.i.d. from P. Let  $\widehat{P}_n$  be the empirical distribution from the n examples. Consider the  $\chi^2$  divergence, where we use the function  $f(t) = \frac{1}{2}(t-1)^2$  as the f-divergence, following Definition 1. We denote the f-divergence as  $D_{\chi^2}(Q|P)$ . For some  $\rho > 0$ , define the class of distributions  $\mathcal{P}_{n,\rho}$  that we want to be robust against as:

$$\mathcal{P}_{n,\rho} := \left\{ \text{Distribution } P : D_{\chi^2} \left( P \| \widehat{P}_n \right) \le \frac{\rho}{n} \right\}$$
 (5.16)

Notice that, in this collection of "close" distributions, as  $n \to \infty$ , we get closer and closer to our original distribution P. We are sticking very close to our original distribution, and, for  $n \to \infty$  at the limit, this is just standard optimizing for the original distribution P (which we can just do via ERM). Maximizing over this collection gives us the *empirical likelihood upper confidence bound*:

$$R_{n}(\theta, \mathcal{P}_{n,\rho}) := \max_{P \in \mathcal{P}_{n,\rho}} \mathbb{E}_{P}[\ell(\theta; Z)] = \max_{p: D_{\chi^{2}}(P \| \hat{P}_{n}) \le \frac{\rho}{n}} \sum_{i=1}^{n} p_{i}\ell(\theta; Z_{i}).$$
 (5.17)

Solving for the best model that optimizes (5.17) is just a DRO problem. We'll denote this best DRO model as:

$$\hat{\theta}^{\text{rob}} \in \underset{\theta \in \Theta}{\operatorname{argmin}} \left\{ R_n(\theta, \mathcal{P}_{n,\rho}) = \max_{p: D_{\chi^2}(P \| \hat{P}_n) \le \frac{\rho}{n}} \sum_{i=1}^n p_i \ell(\theta; Z_i) \right\}.$$
 (5.18)

The difference between  $\hat{\theta}^{\text{var}}$  from (5.15) and  $\hat{\theta}^{\text{rob}}$  from (5.18) is that  $\hat{\theta}^{\text{rob}}$  can actually be efficiently solved for using DRO methods! The problem is convex, and we can use any of the methods in Section 5.3 to solve it. It turns out that (5.17) actually converges to the term being optimized in (5.15), which connects DRO to the direct variance-regularized risk.

**Theorem 2** (Equivalence of DRO and Variance-Regularized Risk). For general f-divergences and bounded loss  $\ell(\theta; Z) \leq M$ ,

$$R_n(\theta; \mathcal{P}_{n,\rho}) = \widehat{R}_n(\theta) + \sqrt{\frac{2\rho \operatorname{Var}_{\widehat{P}_n}(\ell(\theta; Z)))}{n}} + \operatorname{Rem}_n(\theta).$$
 (5.19)

Let  $\sigma^2(\theta) := \operatorname{Var}(\ell(\theta; Z))$ . Also,  $\operatorname{Rem}_n(\theta) \leq \frac{\sqrt{12}\rho M}{n}$  and  $\operatorname{Rem}_n(\theta) = 0$  with probability at least  $1 - \exp\left(-\frac{n\sigma^2(\theta)}{36M^2}\right)$ .

We will prove Theorem 2 below. Using Theorem 2, we get the following guarantee on the true risk of the DRO model which optimizes  $R_n(\theta, \mathcal{P}_{n,\rho})$ . Recall the definition of  $\hat{\theta}^{\text{rob}}$  from (5.18).

**Theorem 3.** Let  $\rho = \log \frac{1}{\delta} + d \log n$ . Then, with probability at least  $1 - \delta$ ,

$$R(\hat{\theta}^{\text{rob}}) \leq R_n(\hat{\theta}^{\text{rob}}, \mathcal{P}_{n,\rho}) + \frac{crM\rho}{n}$$

$$\leq \min_{\theta \in \Theta} \left\{ R(\theta) + \sqrt{\frac{2\rho \text{Var}_{\widehat{P}_n}(\ell(\theta; Z)))}{n}} \right\} + \frac{crM\rho}{n},$$

where  $R(\theta)$  is the standard average-case risk from (5.13) and  $\mathcal{P}_{n,\rho}$  is from (5.16).

The thrust of Theorem 3 is that running DRO allows us to achieve the optimal bias-variance tradeoff we wanted in (5.14) with respect to the standard measure of risk,  $R(\theta)$ . Further, this actually beats ERM! Denote  $R(\theta^*) := \inf_{\theta \in \Theta} R(\theta)$ , the true minimizer of standard risk. ERM gives us the following guarantee:

$$R(\hat{\theta}^{\text{erm}}) \le R(\theta^*) + \sqrt{\frac{2\rho M R(\theta^*)}{n}} + \frac{CM\rho}{n}.$$
 (5.20)

If  $Var(\ell(\theta; X)) \ll MR(\theta^*)$ , then the bound in Theorem 3 is actually *tighter* than that of (5.20). This shows DRO beating ERM, which provides a possible theoretical explanation for Figure 5.4 in Section 5.3.

Finally, we provide the proof (sketch) of Theorem 2.

*Proof.* Denote  $z_i := \ell(\theta, Z_i)$  and denote  $u_i = p_i - \frac{1}{n}$  and denote  $\overline{z}$  and  $s_n^2$  the sample mean and sample variance, respectively. With this notation, the empirical likelihood upper confidence bound becomes:

$$R_n(\theta; \mathcal{P}_{n,\rho}) = \max_{p} \left\{ \langle p, z \rangle : D_{\chi^2} \left( p \| \mathbf{1}/n \right) \le \frac{\rho}{n} \right\}$$

Using the definition of  $\chi^2$  divergence,

$$= \max_{p} \left\{ \langle p, z \rangle : \frac{1}{n} \sum_{i=1}^{n} (np_{i} - 1)^{2} \le \frac{\rho}{n}, p^{\top} \mathbf{1} = 1, p \ge 0 \right\}.$$

Using the change of variable from  $u_i := p_i - \frac{1}{n}$ , we get:

$$\begin{split} &= \overline{z} + \max_{u} \left\{ \left\langle u, z - \overline{z} \right\rangle : \|u\|^{2} \leq \frac{\rho}{n^{2}}, u^{\top} \mathbf{1} = 1, u \geq -\frac{\mathbf{1}}{n} \right\} \\ &\leq \overline{z} + \frac{\sqrt{2\rho}}{n} \|z - \overline{z}\|_{2} = \overline{z} + \sqrt{\frac{2\rho}{n} s_{n}^{2}} \qquad \text{(by Cauchy-Schwarz)}. \end{split}$$

The final inequality is tight if, for all i,

$$u_i = \frac{1}{n} \sqrt{\frac{2\rho}{ns_n^2}} (z_i - \overline{z}) \ge -\frac{1}{n}.$$